

TCCR4M048-F

Telecentric CORE lens for 4/3" detectors, magnification 0.369 x, F-mount

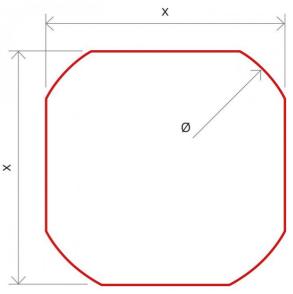
SPECIFICATIONS

Part number		TCCR4M048-F
Magnification	(×)	0.369
Image shape dimension (8)	(Ø, x mm)	Ø=22.1, x=18.8
Phase adjustment (7)		Yes
Object field of view 7		
with IMX174/IMX249 13.3 mm diag w x h 11.35 x 7.13	(mm x mm)	30.6 x 19.2
with KAI-2020 14.8 mm diagonal w x h 11.84 x 8.88	(mm x mm)	32.1 x 24.1
with IMX253/IMX304 17.6 mm diag w x h 14.16 x 10.37	(mm x mm)	38.5 x 28.2
with KAI-4022/4021 21.5 mm diagonal w x h 15.2 x 15.2	(mm x mm)	41.2 x 41.2
with KAI-08050 22.6 mm diagonal w x h 18.1 x 13.6	(mm x mm)	49.1 x 36.9

Optical specifications

Working distance (1)	(mm)	133.4
wF/# (2)		16
Telecentricity typical (max) (3)	(deg)	< 0.08 (0.10)
Distortion typical (max) (4)	(%)	< 0.08 (0.10)
Field depth (5)	(mm)	9.7
CTF@ 50 lp/mm	(%)	> 40
Mechanical specifications		
Mount (6)		F
A	(mm)	77
В	(mm)	118
с	(mm)	163
Mass	(g)	1311





Compatibility

LTCLCR048-x, CMHOCR048, CMPTCR048, LTCLHP048-x

Last update: 2019-05-10

NOTES

- 1. Working distance: distance between the front end of the mechanics and the object. Set this distance within +/-3% of the nominal value for maximum resolution and minimum distortion.
- 2. Working F-number (wF/#): the real F-number of a lens when used as a macro. Lenses with smaller apertures can be supplied on request.
- Maximum slope of chief rays inside the lens: when converted to milliradians, it gives the maximum measurement error for any millimeter of object displacement. Typical (average production) values and maximum (guaranteed) values are listed.
- 4. Percent deviation of the real image compared to an ideal, undistorted image: typical (average production) values and maximum (guaranteed) values are listed.
- 5. At the borders of the field depth the image can be still used for measurement but, to get a perfectly sharp image, only half of the nominal field depth should be considered. Pixel size used for calculation is 5.5 µm.
- 6. In case the of vignetting, FOV dimensions are indicated with " \emptyset = , x= ", where " \emptyset =" stands for diameter and "x=" indicates the nominal FOV height and length (see <u>Tech Info</u> for related drawing).
- 7. Indicates the availability of an integrated camera phase adjustment feature.
- Indicates the dimensions and shape of image, where "Ø =" stands for diameter and "x=" indicates the nominal image height and length (see <u>Tech Info</u> for related drawing)

COMPATIBLE PRODUCTS

Despite the efforts made to generate an error-free compatibility list, we always recommend to consult the Opto Engineering® **technical support** department before purchasing a compatible product. Opto Engineering® shall not be liable for any damage or malfunctioning caused by the incorrect selection of a compatible product.

Image shape dimensions (\emptyset , x)

All product specifications and data are subject to change without notice to improve reliability, functionality, design or other. Photos and pictures are for illustration purposes only.



High-performance telecentric illuminators

LTCLHP048-R	Telecentric HP illuminator, beam diameter 60 mm, red
LTCLHP048-G	Telecentric HP illuminator, beam diameter 60 mm, green
LTCLHP048-B	Telecentric HP illuminator, beam diameter 60 mm, blue
LTCLHP048-W	Telecentric HP illuminator, beam diameter 60 mm, white
	P CORE series
Ultra c	ompact telecentric illuminators
LTCLCR048-R	Telecentric CORE illuminator, beam dimensions \emptyset = 56; x = 50, red
LTCLCR048-G	Telecentric CORE illuminator, beam dimensions \emptyset = 56; x = 50, green
LTCLCR048-W	Telecentric CORE illuminator, beam dimensions \emptyset = 56; x = 50, white
LTBC S	eries
Contin	uos LED backlight
.TBC114114-W	Continuos LED backlight, 114x114 illumination area, white
TBC114114-G	Continuos LED backlight, 114x114 illumination area, green
00 auto	carias
СМНО	Series
Clampi	ing mechanics
CMHORBCR048	Clamping mechanics robotics
СМНО	CR series
Clampi	ng mechanics CORE series
	mping mechanics for CORE telecentric lenses and illuminators TCCRxx48 and ILCR048-x
СМРТС	R series
CORE s	series mounting plates
CMPTCR048 Mec	hanical components designed for CORE telecentric lenses and illuminators Ø 48mm
mvBlue	eFOX3-2 series
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USB3 v	ision camera with Sony Pregius CMOS sensors
RT-mvBF3-2089a	USB3 Vision camera with Sony Pregius CMOS sensor IMX267
T-mvBF3-2089	USB3 Vision camera with Sony Pregius CMOS sensor IMX255
T-mvBF3-2124a	USB3 Vision camera with Sony Pregius CMOS sensor IMX304
RT-mvBF3-2124	USB3 Vision camera with Sony Pregius CMOS sensor IMX253
🛐 🜒 myBlue	eCOUGAR series
GigE &	Dual GigE Vision cameras
RT-mvBC-X109b	Camera with interface GigE (1GB/s), sensor size 1", mpixel 8.95, resolution 4112 x 2176, sensor name IMX267, sensor type CMOS
RT-mvBC-XD109b	Camera with interface Dual GigE (2GB/s), sensor size 1", mpixel 8.95, resolution 4112 X 2176, sensor name IMX267, sensor type CMOS
RT-mvBC-X1012b	Camera with interface GigE (1GB/s), sensor size 1.1", mpixel 12.37, resolution 4112 x 3008, sensor name IMX304, sensor type CMOS
RT-mvBC-XD107	Camera with interface Dual GigE (2GB/s), sensor size 1.1", mpixel 7.1, resolution 3216 x 2208, sensor name IMX420, sensor type CMOS
RT-mvBC-XD1012b	
	4112 x 3008, sensor name IMX304, sensor type CMOS

TCLIB Suite

Software library & stand-alone tools for the optimization of telecentric setups

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COE HR AS-X series

20MP, 26MP and 29MP area scan cameras for high-speed applications

COE-200-M-POE-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Gray, GigE, 6 fps, POE, C - mount, Glass filter
COE-200-C-POE-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Color, GigE, 6 fps, POE, C - mount, Infrared cut filter
COE-200-M-USB-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Gray, 14 fps, C - mount, Glass filter
COE-200-C-USB-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Color, 14 fps, C - mount, Infrared cut filter