

TCCR4M096-C

Telecentric CORE lens for 4/3" detectors, magnification 0.186 x, C-mount

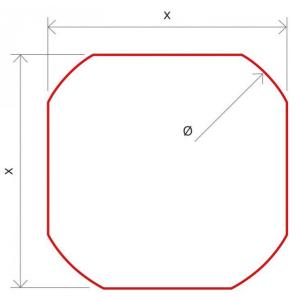
SPECIFICATIONS

| Part number | | TCCR4M096-C |
|---|-----------|----------------|
| Magnification | (×) | 0.186 |
| Image shape dimension (8) | (Ø, x mm) | Ø=22.5, x=18.6 |
| Phase adjustment (7) | | Yes |
| Object field of view7 | | |
| with IMX174/IMX249 13.3 mm diag w x h 11.35 x 7.13 | (mm x mm) | 60.8 x 38.2 |
| with KAI-2020 14.8 mm diagonal w x h 11.84 x 8.88 | (mm x mm) | 63.5 x 47.6 |
| with IMX253/IMX304 17.6 mm diag w x h 14.16 x 10.37 | (mm x mm) | 76.3 x 55.9 |
| with KAI-4022/4021 21.5 mm diagonal w x h 15.2 x 15.2 | (mm x mm) | 81.7 x 81.7 |
| with KAI-08050 22.6 mm diagonal w x h 18.1 x 13.6 | (mm x mm) | 97.3 x 73.1 |
| | | |

Optical specifications

| Working distance (1) | (mm) | 278.6 |
|----------------------------------|-------|---------------|
| wF/# (2) | | 16 |
| Telecentricity typical (max) (3) | (deg) | < 0.05 (0.10) |
| Distortion typical (max) (4) | (%) | < 0.04 (0.10) |
| Field depth (5) | (mm) | 38.2 |
| CTF@ 50 lp/mm | (%) | > 35 |
| Mechanical specifications | | |
| Mount (6) | | С |
| A | (mm) | 139 |
| В | (mm) | 172 |
| C | (mm) | 254 |
| Mass | (g) | 4389 |





Compatibility

LTCLCR096-x, CMHOCR096, CMPTCR096, LTCLHP096-x

Last update: 2019-05-10

NOTES

- 1. Working distance: distance between the front end of the mechanics and the object. Set this distance within +/-3% of the nominal value for maximum resolution and minimum distortion.
- 2. Working F-number (wF/#): the real F-number of a lens when used as a macro. Lenses with smaller apertures can be supplied on request.
- Maximum slope of chief rays inside the lens: when converted to milliradians, it gives the maximum measurement error for any millimeter of object displacement. Typical (average production) values and maximum (guaranteed) values are listed.
- 4. Percent deviation of the real image compared to an ideal, undistorted image: typical (average production) values and maximum (guaranteed) values are listed.
- 5. At the borders of the field depth the image can be still used for measurement but, to get a perfectly sharp image, only half of the nominal field depth should be considered. Pixel size used for calculation is 5.5 µm.
- 6. In case the of vignetting, FOV dimensions are indicated with " \emptyset = , x= ", where " \emptyset =" stands for diameter and "x=" indicates the nominal FOV height and length (see <u>Tech Info</u> for related drawing).
- 7. Indicates the availability of an integrated camera phase adjustment feature.
- Indicates the dimensions and shape of image, where "Ø =" stands for diameter and "x=" indicates the nominal image height and length (see <u>Tech Info</u> for related drawing)

COMPATIBLE PRODUCTS

Despite the efforts made to generate an error-free compatibility list, we always recommend to consult the Opto Engineering® **technical support** department before purchasing a compatible product. Opto Engineering® shall not be liable for any damage or malfunctioning caused by the incorrect selection of a compatible product.

Image shape dimensions (\emptyset , x)

All product specifications and data are subject to change without notice to improve reliability, functionality, design or other. Photos and pictures are for illustration purposes only.



High-performance telecentric illuminators

| LTCLHP096-G | Telecentric HP illuminator, beam diameter 120 mm, green |
|---------------------------------|---|
| LTCLHP096-R | Telecentric HP illuminator, beam diameter 120 mm, red |
| LTCLHP096-B | Telecentric HP illuminator, beam diameter 120 mm, blue |
| LTCLHP096-W | Telecentric HP illuminator, beam diameter 120 mm, white |
| - 🔛 | P CORE series |
| Ultra co | ompact telecentric illuminators |
| LTCLCR096-R | Telecentric CORE illuminator, beam dimensions \emptyset = 120; x = 99, red |
| LTCLCR096-G | Telecentric CORE illuminator, beam dimensions Ø = 120; x = 99, green |
| LTCLCR096-W | Telecentric CORE illuminator, beam dimensions \emptyset = 120; x = 99, white |
| | eries |
| Continu | uos LED backlight |
| Continu | JUS LED Dacklight |
| LTBC174174-W | Continuos LED backlight, 174x174 illumination area, white |
| LTBC174174-G | Continuos LED backlight, 174x174 illumination area, green |
| A | |
| СМНО | CR series |
| Clampi | ing mechanics CORE series |
| | |
| | mping mechanics for CORE telecentric lenses and illuminators TCCRxx96 and LCR096-x |
| - | |
| СМРТС | 'R series |
| CORE s | series mounting plates |
| | |
| CMPTCR096 Mec | hanical components designed for CORE telecentric lenses and illuminators Ø 96mm |
| | ries |
| | an alignment machanics |
| Precisio | on alignment mechanics |
| CMTHCR096 | Precision alignment mechanics for CORE telecentric optics 096 |
| a muBlue | |
| | eFOX3-2 series |
| USB3 v | ision camera with Sony Pregius CMOS sensors |
| DTDE2 2000- | |
| RT-mvBF3-2089a RT-mvBF3-2089 | USB3 Vision camera with Sony Pregius CMOS sensor IMX267 |
| RT-mvBF3-2089 | USB3 Vision camera with Sony Pregius CMOS sensor IMX255 USB3 Vision camera with Sony Pregius CMOS sensor IMX304 |
| RT-mvBF3-2124 | USB3 Vision camera with Sony Pregius CMOS sensor IMX253 |
| | |
| 💐 🜒 🛛 mvBlue | eCOUGAR series |
| GigE & | Dual GigE Vision cameras |
| | |
| | Compromite interface Circ. (ICD (a) concercing 11 and 12 and 10 and 1442 |
| RT-mvBC-X109b | Camera with interface GigE (1GB/s), sensor size 1", mpixel 8.95, resolution 4112 x 2176, sensor name IMX267, sensor type CMOS |
| RT-mvBC-XD109b | Camera with interface Dual GigE (2GB/s), sensor size 1", mpixel 8.95, resolution 4112 X 2176, sensor name IMX267, sensor type CMOS |
| RT-mvBC-X1012b | Camera with interface GigE (1GB/s), sensor size 1.1", mpixel 12.37, resolution 4112 x 3008, sensor name IMX304, sensor type CMOS |
| RT-mvBC-XD107 | Camera with interface Dual GigE (2GB/s), sensor size 1.1", mpixel 7.1, resolution 3216 x 2208, sensor name IMX420, sensor type CMOS |
| RT-mvBC-XD1012b | Camera with interface Dual GigE (2GB/s), sensor size 1.1", mpixel 12.37, resolution 4112 x 3008, sensor name IMX304, sensor type CMOS |
| | |

TCLIB Suite

Software library & stand-alone tools for the optimization of telecentric setups

()

COE HR AS-X series

20MP, 26MP and 29MP area scan cameras for high-speed applications

| COE-200-M-POE-070-IR-C | HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Gray, GigE, 6 fps, POE, C - mount, Glass filter |
|------------------------|---|
| COE-200-C-POE-070-IR-C | HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Color, GigE, 6 fps, POE, C - mount, Infrared cut filter |
| COE-200-M-USB-070-IR-C | HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Gray, 14 fps, C - mount, Glass filter |
| COE-200-C-USB-070-IR-C | HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Color, 14 fps, C - mount, Infrared cut filter |