# OPTO ENGINEERING

# TCCR2M120-E

Telecentric CORE lens for 1" detectors, magnification 0.104 x, M42x1 FD 16

#### **SPECIFICATIONS**

ST ECHTCATIONS		
Part number		TCCR2M120-E
Magnification	(x)	0.104
Image shape dimension (8)	(Ø, x mm)	Ø=16.4, x=13.4
Phase adjustment (7)		Yes
Object field of view7		
with IMX174/IMX249 13.3 mm diag w x h 11.35 x 7.13	(mm x mm)	108.7 x 68.3
with KAI-2020 14.8 mm diagonal w x h 11.84 x 8.88	(mm x mm)	113.8 x 85.4
with IMX253/IMX304 17.6 mm diag w x h 14.16 x 10.37	(mm x mm)	Ø=158, x=100
with KAI-4022/4021 21.5 mm diagonal w x h 15.2 x 15.2	(mm x mm)	Ø=158, x=129
with KAI-08050 22.6 mm diagonal w x h 18.1 x 13.6	(mm x mm)	Ø=158, x=129
Optical specifications		
Working distance (1)	(mm)	334.6
wF/# (2)		16
Telecentricity typical (max) (3)	(deg)	< 0.06 (0.10)
Distortion typical (max) (4)	(%)	< 0.08 (0.10)
Field depth (5)	(mm)	122.0
CTF@ 50 lp/mm	(%)	> 40
Mechanical specifications		
Mount (6)		M42x1 FD16.00
A	(mm)	182
В	(mm)	220
С	(mm)	260
Mass	(g)	9311
Compatibility		
LTCLCR120-x, LTCLHP120-x		

# NOTES

Last update: 2019-06-17

- 1. Working distance: distance between the front end of the mechanics and the object. Set this distance within +/- 3% of the nominal value for maximum resolution and minimum distortion.
- 2. Working F-number (wF/#): the real F-number of a lens when used as a macro. Lenses with smaller apertures can be supplied on request.
- Maximum slope of chief rays inside the lens: when converted to milliradians, it gives the maximum
  measurement error for any millimeter of object displacement. Typical (average production) values and
  maximum (guaranteed) values are listed.
- 4. Percent deviation of the real image compared to an ideal, undistorted image: typical (average production) values and maximum (guaranteed) values are listed.
- At the borders of the field depth the image can be still used for measurement but, to get a perfectly sharp image, only half of the nominal field depth should be considered. Pixel size used for calculation is 5.5 µm.
- 6. In case the of vignetting, FOV dimensions are indicated with "Ø = , x= ", where "Ø =" stands for diameter and "x=" indicates the nominal FOV height and length (see <u>Tech Info</u> for related drawing).
- 7. Indicates the availability of an integrated camera phase adjustment feature.
- 8. Indicates the dimensions and shape of image, where "Ø =" stands for diameter and "x=" indicates the nominal image height and length (see <a href="Tech Info">Tech Info</a> for related drawing)

#### COMPATIBLE PRODUCTS

Despite the efforts made to generate an error-free compatibility list, we always recommend to consult the Opto Engineering® technical support department before purchasing a compatible product. Opto Engineering® shall not be liable for any damage or malfunctioning caused by the incorrect selection of a compatible product.



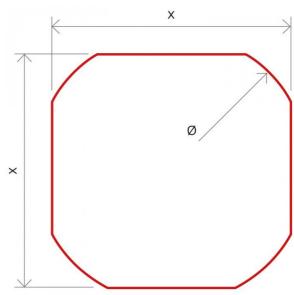


Image shape dimensions (Ø, x )

All product specifications and data are subject to change without notice to improve reliability, functionality, design or other. Photos and pictures are for illustration purposes only.



#### High-performance telecentric illuminators

LTCLHP120-R	Telecentric HP illuminator, beam diameter 150 mm, red
LTCLHP120-G	Telecentric HP illuminator, beam diameter 150 mm, green
LTCLHP120-W	Telecentric HP illuminator, beam diameter 150 mm, white



# LTCLHP CORE series

#### Ultra compact telecentric illuminators

LTCLCR120-R	Telecentric CORE illuminator, beam dimensions Ø = 156, x = 130, red, 630 nm
LTCLCR120-G	Telecentric CORE illuminator, beam dimensions Ø = 156, x = 130, green, 520 nm
LTCLCR120-W	Telecentric CORE illuminator, beam dimensions Ø = 156, x = 130, white



# LTBC series

#### Continuos LED backlight

LTBC174174-W	Continuos LED backlight, 174x174 illumination area, white
LTBC174174-G	Continuos LED backlight, 174x174 illumination area, green



# mvBlueFOX3-2 series

#### USB3 vision camera with Sony Pregius CMOS sensors

RT-mvBF3-2024a	USB3 Vision camera with Sony Pregius CMOS sensor IMX249
RT-mvBF3-2024	USB3 Vision camera with Sony Pregius CMOS sensor IMX174
RT-mvBF3-2089a	USB3 Vision camera with Sony Pregius CMOS sensor IMX267
RT-mvBF3-2089	USB3 Vision camera with Sony Pregius CMOS sensor IMX255



#### mvBlueCOUGAR series

# GigE & Dual GigE Vision cameras

RT-mvBC-X104f	Camera with interface GigE (1GB/s), sensor size 1/1.2", mpixel 2.35, resolution 1936 $\times$ 1216, sensor name IMX249, sensor type CMOS
RT-mvBC-XD104d	Camera with interface Dual GigE (2GB/s), sensor size 1/1.2", mpixel 2.35, resolution 1936 x 1214, sensor name IMX174, sensor type CMOS
RT-mvBC-X109b	Camera with interface GigE (1GB/s), sensor size 1", mpixel 8.95, resolution 4112 x 2176, sensor name IMX267, sensor type CMOS
RT-mvBC-XD109b	Camera with interface Dual GigE (2GB/s), sensor size 1", mpixel 8.95, resolution 4112 X 2176, sensor name IMX267, sensor type CMOS



# TCLIB Suite

Software library & stand-alone tools for the optimization of telecentric setups

TCLIB-01 Software library & stand-alone tools for the optimization of telecentric setups



# COE HR AS-X series

20MP, 26MP and 29MP area scan cameras for high-speed applications  $\,$ 

COE-200-M-POE-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Gray, GigE, 6 fps, POE, C - mount, Glass filter
COE-200-C-POE-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 $\times$ 3648, 20.4 MP, 2.4 pix, 1", Color, GigE, 6 fps, POE, C - mount, Infrared cut filter
COE-200-M-USB-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 $\times$ 3648, 20.4 MP, 2.4 pix, 1", Gray, 14 fps, C - mount, Glass filter
COE-200-C-USB-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 $\times$ 3648, 20.4 MP, 2.4 pix, 1", Color, 14 fps, C - mount, Infrared cut filter