OPTO ENGINEERING

TCCR2M080-C

Telecentric CORE lens for 1" detectors, magnification 0.160 x, C-mount

SPECIFICATIONS

Part number		TCCR2M080-C
Magnification	(x)	0.160
Image shape dimension (8)	(Ø, x mm)	Ø=16.3, x=13.8
Phase adjustment (7)		Yes
Object field of view7		
with IMX174/IMX249 13.3 mm diag w x h 11.35 x 7.13	(mm x mm)	70.6 x 44.4
with KAI-2020 14.8 mm diagonal w x h 11.84 x 8.88	(mm x mm)	74.0 x 55.5
with IMX253/IMX304 17.6 mm diag w x h 14.16 x 10.37	(mm x mm)	Ø=102, x=65
with KAI-4022/4021 21.5 mm diagonal w x h 15.2 x 15.2	(mm x mm)	Ø=102, x=86
with KAI-08050 22.6 mm diagonal w x h 18.1 x 13.6	(mm x mm)	Ø=102, x=85
Optical specifications		
Working distance (1)	(mm)	226.8
wF/# (2)		16
Telecentricity typical (max) (3)	(deg)	< 0.04 (0.08)
Distortion typical (max) (4)	(%)	< 0.05 (0.10)
Field depth (5)	(mm)	51.6
CTF@ 50 lp/mm	(%)	> 40
Mechanical specifications		
Mount (6)		С
A	(mm)	119
В	(mm)	145
С	(mm)	205
Mass	(g)	3082

Compatibility

LTCLCR080-x, CMHOCR080, CMPTCR080, LTCLHP080-x

Last update: 2019-05-10

NOTES

- 1. Working distance: distance between the front end of the mechanics and the object. Set this distance within +/- 3% of the nominal value for maximum resolution and minimum distortion.
- 2. Working F-number (wF/#): the real F-number of a lens when used as a macro. Lenses with smaller apertures can be supplied on request.
- 3. Maximum slope of chief rays inside the lens: when converted to milliradians, it gives the maximum measurement error for any millimeter of object displacement. Typical (average production) values and maximum (guaranteed) values are listed.
- 4. Percent deviation of the real image compared to an ideal, undistorted image: typical (average production) values and maximum (guaranteed) values are listed.
- 5. At the borders of the field depth the image can be still used for measurement but, to get a perfectly sharp image, only half of the nominal field depth should be considered. Pixel size used for calculation is 5.5 µm.
- 6. In case the of vignetting, FOV dimensions are indicated with "Ø = , x= ", where "Ø =" stands for diameter and "x=" indicates the nominal FOV height and length (see <u>Tech Info</u> for related drawing).
- 7. Indicates the availability of an integrated camera phase adjustment feature.
- 8. Indicates the dimensions and shape of image, where "Ø =" stands for diameter and "x=" indicates the nominal image height and length (see Tech Info for related drawing)

COMPATIBLE PRODUCTS

Despite the efforts made to generate an error-free compatibility list, we always recommend to consult the Opto Engineering® technical support department before purchasing a compatible product. Opto Engineering® shall not be liable for any damage or malfunctioning caused by the incorrect selection of a compatible product.



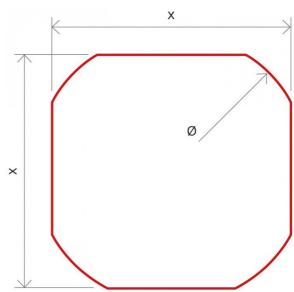


Image shape dimensions (Ø, x)

All product specifications and data are subject to change without notice to improve reliability, functionality, design or other. Photos and pictures are for illustration purposes only.



High-performance telecentric illuminators

LTCLHP080-R	Telecentric HP illuminator, beam diameter 100 mm, red
LTCLHP080-G	Telecentric HP illuminator, beam diameter 100 mm, green
LTCLHP080-B	Telecentric HP illuminator, beam diameter 100 mm, blue
LTCLHP080-W	Telecentric HP illuminator, beam diameter 100 mm, white



LTCLHP CORE series

Ultra compact telecentric illuminators

LTCLCR080-R	Telecentric CORE illuminator, beam dimensions Ø = 98; x = 90, red
LTCLCR080-G	Telecentric CORE illuminator, beam dimensions Ø = 98; x = 90, green
LTCLCR080-W	Telecentric CORE illuminator, beam dimensions Ø = 98; x = 90, white



LTBC series

Continuos LED backlight

LTBC114114-W	Continuos LED backlight, 114x114 illumination area, white
LTBC114114-G	Continuos LED backlight, 114x114 illumination area, green



CMHOCR series

Clamping mechanics CORE series

CMHOCR080	Clamping mechanics for CORE telecentric lenses and illuminators TCCRxx80 and
	LTCLCR080-x



CMPTCR series

CORE series mounting plates

 ${\tt CMPTCR080} \quad \text{Mechanical components designed for CORE telecentric lenses and illuminators } \emptyset \ 80 mm$



Precision alignment mechanics

CMTHCR080	Precision alignment mechanics for CORE telecentric optics 080;	
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mvBlueFOX3-2 series

USB3 vision camera with Sony Pregius CMOS sensors

RT-mvBF3-2024a	USB3 Vision camera with Sony Pregius CMOS sensor IMX249
RT-mvBF3-2024	USB3 Vision camera with Sony Pregius CMOS sensor IMX174
RT-mvBF3-2089a	USB3 Vision camera with Sony Pregius CMOS sensor IMX267
RT-mvBF3-2089	USB3 Vision camera with Sony Pregius CMOS sensor IMX255



mvBlueCOUGAR series

GigE & Dual GigE Vision cameras

RT-mvBC-X104f	Camera with interface GigE (1GB/s), sensor size 1/1.2", mpixel 2.35, resolution 1936 x 1216, sensor name IMX249, sensor type CMOS
RT-mvBC-XD104d	Camera with interface Dual GigE (2GB/s), sensor size 1/1.2", mpixel 2.35, resolution 1936 x 1214, sensor name IMX174, sensor type CMOS
RT-mvBC-X109b	Camera with interface GigE (1GB/s), sensor size 1", mpixel 8.95, resolution 4112 x 2176, sensor name IMX267, sensor type CMOS
RT-mvBC-XD109b	Camera with interface Dual GigE (2GB/s), sensor size 1", mpixel 8.95, resolution 4112 X 2176, sensor name IMX267, sensor type CMOS



TCLIB Suite

Software library & stand-alone tools for the optimization of telecentric setups



20MP, 26MP and 29MP area scan cameras for high-speed applications

COE-200-M-POE-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 × 3648, 20.4 MP, 2.4 pix, 1", Gray, GigE, 6 fps, POE, C - mount, Glass filter
COE-200-C-POE-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472×3648 , 20.4 MP, 2.4 pix, 1 ", Color, GigE, 6 fps, POE, C - mount, Infrared cut filter
COE-200-M-USB-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 \times 3648, 20.4 MP, 2.4 pix, 1", Gray, 14 fps, C - mount, Glass filter
COE-200-C-USB-070-IR-C	HR Area Scan camera IMX183, CMOS, Rolling shutter, 5472 \times 3648, 20.4 MP, 2.4 pix, 1", Color, 14 fps, C - mount, Infrared cut filter